1. **Nonlinear Equations** Given s alar equation, $f(x) = 0$

- a es ri e \mathbb{N} e ons \mathbb{N} e od \bullet e an \mathbb{N} e od for a ro \mathbb{N} a in e solution.
- a e sufficient conditions for N_e on and e and converge. If satisfied at at at a ill ea onver
	- \bullet e rop ρ onver en e_f or \mathbb{N} e on $s \uparrow e$ od.
- d rie Newton's \mathbf{M}_e od as a ed ointieration. \bullet a es \mathbf{F} ientonditions for a eneral ed oin i era ion o onver e.
- e ly erierion for ed oin iteration of N e on s λ eried and develop and dernate roof or \mathbf{N} e on s \mathbf{N} e od.

Solution

a Newton's \mathbb{R} e od Given x_0 le

$$
x_{n+1} \quad x_n - \frac{f x_n}{f x_n}, \qquad n \quad 0.
$$

 \bullet e an Λ _le od Given x_0 x_1 let

$$
x_{n+1} \quad x_n - f \; x_n \; \frac{x_n - x_{n-1}}{f \; x_n \; - f \; x_{n-1}} \qquad n \quad 1.
$$

(b) Newton's $\oint e \cdot d\theta \cdot e \cdot f = 0.$ as $\oint e \cdot a \cdot e \cdot e \cdot e$ is san interval $E = -\frac{1}{2}$ s_{\rightarrow} a \hat{f} *x* f *x* and f *x* are on in ϕ s on *E* and

$$
\frac{\ln a_{x} f x}{\ln a_{x} f x} M,
$$

and $M < 1.0$. en_f or any $x_0 \in E$ **Ne** on \mathbb{A} **e** od ill onver e i ra e 2.0. \bullet e and \bullet e odnot e same assumptions if x_0 and x_1 are in E , the \bullet \bullet e and $\frac{1}{2}$ e od ill onver e i rae $\frac{1+5}{2}$ ~ 1.62 .

• ee inson, a es $5/60$.

d e ne

$$
g x \quad x - \frac{f x}{f x}.
$$

 $\mathbb{N}\mathrm{e}\quad \mathrm{on}\; \mathfrak{M}\;\; \mathrm{e}\quad \mathrm{od}\;\; \mathrm{an}\;\; \mathrm{e}\;\; \mathrm{as}\;\; \mathrm{as}\;\; \mathrm{Given}\; x$

Numerical quadrature:

 $2.$ Assume that a quadrature rule, when discretizing with n nodes, possesses an error expansion of the form

$$
I - I_n = \frac{c_1}{n} + \frac{c_2}{n^2} + \frac{c_3}{n^3} + \dots
$$

Assume also that we, for a certain value of *n*, have numerically evaluated I_n , I_{2n} and I_{3n} .

- Derive the best approximation that you can for the true value I of the integral. a.
- The error in this approximation will be of the form $O(n^{-p})$ for a certain value of p. What \mathbf{b} . is this value for p ?

Solution:

With three numerically evaluated values, we can solve for three variables. For these we a. want to choose *I*, c_1 and c_2 , at which point we only care about the obtained value for *I*.
Abbreviating $\frac{c_1}{n} = d_1$ and $\frac{c_2}{n^2} = d_2$, we thus obtain the relations

$$
\begin{array}{rcl}\n\hat{I} & I - I_n & = & d_1 + d_2 \\
\hat{I} & I - I_{2n} & = & \frac{1}{2}d_1 + \frac{1}{4}d_2 \\
\hat{I} & I - I_{3n} & = & \frac{1}{3}d_1 + \frac{1}{9}d_2\n\end{array}
$$

or, written in the usual linear system form (separating 'knowns' from 'unknowns')

$$
\begin{bmatrix} 1 & -1 & -1 \\ 1 & -\frac{1}{2} & -\frac{1}{4} \\ 1 & -\frac{1}{3} & -\frac{1}{9} \end{bmatrix} \begin{bmatrix} I \\ d_1 \\ d_2 \end{bmatrix} = \begin{bmatrix} I_n \\ I_{2n} \\ I_{3n} \end{bmatrix}
$$

from which follows

$$
I=\frac{1}{2}(I_n-8I_{2n}+9I_{3n}).
$$

With the first two terms in the error expansion eliminated, it will continue from the third \mathbf{b} . term and onwards (with modified coefficients), i.e. the error in the approximation above will be of the form $O(n^{-3})$.

Interpolation / Approximation:

3. The *General Hermite interpolation problem* amounts to finding a polynomial *p*(*x*) of degree $-1 + -2 + ... + -n - 1$ that satisfies

$$
p^{(i)}(x_1) = y_1^{(i)}, \quad i = 0, 1, \dots, -1 - 1
$$

\n
$$
\vdots
$$

\n
$$
p^{(i)}(x_n) = y_n^{(i)}, \quad i = 0, 1, \dots, -1 - 1,
$$

where the superscripts denotes derivatives, that is, we specify the first \cdot *j* − 1 derivatives at the point x_i , for $i = 1, 2, ..., n$. Show that this problem has a unique solution whenever the x_i are distinct.

Hint: Set up the linear system for a small problem, recognize the pattern, and prove the general result.

Solution:

In all, there are $-\frac{1}{2} + \frac{1}{2} + \ldots + \frac{1}{n} = N$ conditions. Let the interpolation polynomial of degree $N-1$ be $p(x) = 0$, p system for the coefficients:

The task is to show that this $N\%N$ coefficient matrix is nonsingular, as this will imply both existence and uniqueness. One way to do this is to let the right hand side (RHS) be zero, and show that the problem then has only the zero solution.

With the RHS zero, the conditions that are imposed require $p(x)$ to have a zero of degree -1 at *x*₁, i.e. a factor $(x - x_1)^{-1}$; then likewise a factor of $(x - x_2)^{-2}$, etc. These required factors will imply that the polynomial $p(x)$ will have a total of *N* zeros (counting multiplicities). This is one above the actual degree of $p(x)$, implying that all the coefficients of $p(x)$ must be zero.

4. **Linear Algebra**

 \bullet onsider e *n i n* nonsin \bullet \bullet *A* is *n n n nonsin* \bullet *A is iven by*

$$
A \qquad \sum a^{-2/1/2}
$$

(a) Construct the perturbation, *∂A*, with smallest Frobenius norm such that *A − ∂A* is $\sin \theta$ ar. in secone φ e **fh** ary det**i** ositions φ *A*.

 \bullet learly

$$
A - A \quad U \Sigma - V
$$

is $\sin \theta = \arctan \theta$.

enoe e ol \mathbf{u}_1 is φ *U* = $\underline{u}_1, \underline{u}_2, \ldots, \underline{u}_n$ and *V* = $\underline{v}_1, \underline{v}_2, \ldots, \underline{v}_n$. e_f a = a *U* and *V* are π ^{*n*} *i* lies a <u>*u*_{*y*} *v*_{*l*} *v*_{*l*} *i*_{*f*} or *j* 1*, ..., n*. e an rie</u>

$$
A \qquad _n \underline{u}_n \underline{v}_n
$$

and e Fro eni_s norm is

$$
A^2 \qquad \frac{2}{n} \sum \sum_{n=1}^{\infty} \left| \underline{u}_n \right|^{2} \left| \underline{v}_n \right|^{2} \qquad \frac{2}{n},
$$

or

∂A ⁿ

• gose *A* is any er q a ion sq a *A* − *A* is sin dar. en ere e is s a ve or φ in length, denoted $y \underline{w}$, s_n a

Aw ∂Aw.

 $N₀$

$$
\mathbf{m} \lim_{z \to 0} \frac{A_Z}{Z} \mathbf{m} \lim_{z \to 1} A_W
$$

 \rightarrow e largest singular value of *A*^{\uparrow} \rightarrow e reater than or equal to *n*. Since \Box iliaion y a unitary matrix does not can e e Frobenius norm, the Frobenius nor nom ρ a eneral a ri is

A $\sum_{1}^{2} 1 \frac{1}{2}$

 \rightarrow ^S

∂A ≥ ⁿ.

d e ans er de ends on *A*. ϵ e^t alles singular value ρ *A* is unique, then the smallest singular value of *A* is unique, then the smallest singular value of *A* is unique, then the smallest singular value of *A* i er **_{***x***}** a ion is *x* \overline{a} , \overline{a} any other per *x* a ion \overline{A} *c* or i \overline{A} − \overline{A} is sin *x* and ill i self ave a second non ero singular value and $\frac{1}{\sqrt{2}}$ a larger Frobenius norm. If there are multiplies of the smallest singular values of *A*, then the are multiple choices of *A*, and *A*, then the smallest singular values of *A*, and i Fro eni s norm equal to *n*.

Numerical ODE:

- 5. Consider using forward Euler (same as AB1; Adams-Bashforth of first order) as a predictor, and the trapezoidal rule (same as AM2; Adams Moulton of second order) as a corrector for solving the ODE $y^0 = f(t, y)$.
	- a. Write down the explicit steps that need to be taken in order to advance the numerical solution from time *tn* to time $t_{n+1} = t_n + k$.
	- b. Determine the order of the combined scheme. In case you know a theorem that gives the order directly, you may quote this *in its general form*, i.e. do not just state the answer in the present special case.
	- c. The figure to the right illustrates the stability domain of the scheme. Prove that $(-2, 0)$ is the leftmost point

6. **Partial Differential Equations**

Consider e seady, sate advection, diffusion equation in one sate dimension

− ^x a x ^xu x)) + *b x ^xu f, x ∈* [0*,* 1]

i of positions *u*(0) $u(1)$ = 0 and the assume is continuous and *a x* is continuous and $a \times b_{\mathfrak{c}}$ or $x = 0, 1$

a es rie e nie dierence $F \circ \mathbf{M}$ e od_cor a ro \mathbf{M} ain e sol_{ution} sin \bullet en ered i eren es \overrightarrow{u} ind i eren es on e advection \overrightarrow{u} and \overrightarrow{v} represent \overrightarrow{u} represent the mesh \overrightarrow{u} represent the mesh \overrightarrow{u} represent the mesh \overrightarrow{u} represent the mesh \overrightarrow{u} represent the m s a in and assume a union mesh. In each case a overdes rie elimear systems A and \overline{A} a \overline{e} FD \overline{e} od yields.

 $\int \cosh \theta$ and $\sinh \theta$ are constant. State a relationship between *a b*, and *h* that ass $\frac{1}{2}$ eigenvalues $\frac{1}{2}$ e linear system are real for $\frac{1}{2}$ eigenvalues *A* and II) Upwind Differences, *A^h*.

For ons an $a > 0$, $b > 0$, se Gers or in o nds o es a lis o nds on e ei envalues **Q** *A* e **upwind** difference **m**^d a ri.

No consider e ara oli e a ion assume *a* > 0 and *b* > 0 are cons and

$$
u \quad a \quad \text{and} \quad x - b \quad u, \qquad x \quad 0, 1
$$

- d rie e **Forward** Ler studie e_c or is equation \sin we energed i erences ind i erences for eadvection \mathbf{d} .
- e riea $\mathbf{39}$ 116en e $24d$ 2 $\sqrt{F21}$, 1.11511241 d00 $/F11$, $/F21$, 1.2013110 d $/F11$, 0.416310

ere *,* $\vert X_{-1}, X_{+1} \rangle$. $\mathbf{e} \bullet$ Centered i erence stencil for the second $\mathbf{e} \bullet$ is

$$
b \times \frac{-u \times -1}{2h} u \times +1
$$
 $b \times u \times_{\mathbf{A}} \frac{h^2}{12} b \times u^{(3)}$

ere \vdots *X* $_{-1}$ *, X* +1.

 $\text{e} \qquad \text{ind} \quad \text{i} \text{ eren e s en il}_{\text{f}} \text{ or } \quad \text{e se ond} \quad \text{d} \text{\normalsize\texttt{\normalsize\texttt{d}}} \quad \text{is} \text{ }_{\text{f}} \text{ or } \text{ } \text{b} \text{ } \text{ } \text{ } \text{x} \text{ } \text{ } > 0$

$$
b x \frac{-u x_{-1}}{h} \qquad b x u x - \frac{h}{2} b x u ,
$$

ere *i* x_{-1}, x and \int or $b x < 0$

$$
b x \frac{-u x_{\text{max}} u x_{+1}}{h} \quad b x u x_{\text{max}} \frac{h}{2} b x u ,
$$

ere $I \, X, X_{+1}$.

ien ered differences, the linear sys $\pmb{\mathbb{Q}}$ is ridia onal, denoted by

$$
\overline{A} \quad \frac{1}{h^2} \text{tri}\left[- a x - h/2 + \frac{1}{2} b x \quad a x - h/2 + a + h/2 - a + h/2 - \frac{h}{2} b x \right]
$$

For $\overline{\hspace{0.1cm}\cdot\hspace{0.1cm}}$ ind differences and constant coefficients, $a >$